

MADE EASY

India's Best Institute for IES, GATE & PSUs

Delhi | Bhopal | Hyderabad | Jaipur | Pune | Kolkata

Web: www.madeeasy.in | **E-mail:** info@madeeasy.in | **Ph:** 011-45124612

EC-EE

SIGNAL & SYSTEM

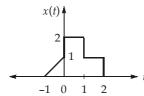
Duration: 1:00 hr. Maximum Marks: 50

Read the following instructions carefully

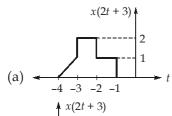
- 1. This question paper contains **30** objective questions. **Q.1-10** carry one mark each and **Q.11-30** carry two marks each.
- 2. Answer all the questions.
- 3. Questions must be answered on Objective Response Sheet (**ORS**) by darkening the appropriate bubble (marked **A**, **B**, **C**, **D**) using HB pencil against the question number. Each question has only one correct answer. In case you wish to change an answer, erase the old answer completely using a good soft eraser.
- 4. There will be **NEGATIVE** marking. For each wrong answer **1/3rd** of the full marks of the question will be deducted. More than one answer marked against a question will be deemed as an incorrect response and will be negatively marked.
- 5. Write your name & Roll No. at the specified locations on the right half of the **ORS**.
- 6. No charts or tables will be provided in the examination hall.
- 7. Choose the **Closest** numerical answer among the choices given.
- 8. If a candidate gives more than one answer, it will be treated as a **wrong answer** even if one of the given answers happens to be correct and there will be same penalty as above to that questions.
- 9. If a question is left blank, i.e., no answer is given by the candidate, there will be **no penalty** for that question.

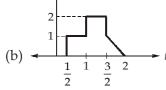
Q.No. 1 to Q.No. 10 carry 1 mark each

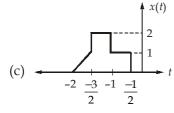
For the signal x(t) shown in figure below: Q.1

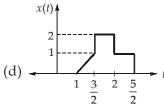


Which of the following signal represents x(2t + 3).









- The Fourier transform of the signal $e^{-(2t-2)}$ Q.2u(t-1) is
 - (a) $\frac{e^{-j2\omega}}{2+j\omega}$ (b) $\frac{e^{-j\omega}}{2+j\omega}$
- Q.3 The energy of the signal

$$x(t) = \left(\frac{\sin 200\pi t}{\pi t}\right) * \left(\frac{\sin 100\pi t}{\pi t}\right)$$

is _____. (* denotes convolution)

- (a) 100
- (b) 50
- (c) 200
- (d) 400
- Let X(z) be the z-transform of a discrete time Q.4 signal x(n), where $x(n) = \sum_{k=0}^{\infty} a^k \delta[n-5k]$. Then X(z) is represented by
- (c) $\frac{z^5}{z^5}$ (d) $\frac{z^4}{z^5}$
- Q.5 The Nyquist sampling rate of the signal x(t) $= (1 + \cos 300\pi t)^2 (\sin 4000\pi t)^2$ is
 - (a) 4.3 kHz
 - (b) 4 kHz
 - (c) 8.6 kHz
 - (d) 8 kHz
- Q.6 Let $x(t) = \frac{\sin(10\pi t)}{\pi t}$ be the continuous time

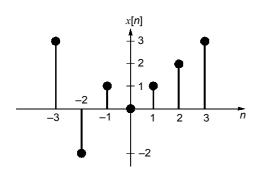
signal, the condition on the sampling interval T_s so that x(t) is uniquely represented by the discrete-time sequence $x[n] = x[nT_s]$ is

- (a) $T_s > \frac{1}{10}$
- (b) $T_s < \frac{1}{10}$ (c) $T_s > 10\pi$
- (d) $T_s < \frac{1}{5\pi}$
- Consider the sequence x[n] = [-2 j5, 1 j, 2]. Q.7

The conjugate anti-symmetric part of the sequence is

- (a) [2-j2.5, j, -2-j2.5]
- (b) [2-j2.5, -j, -2-j2.5]
- (c) [-2-j2.5, -j, 2-j2.5]
- (d) [-2-j2.5, j, -2+j2.5]

Q.8 Consider the sequence given below



the value of $|X(e^{j\pi})|$ is

- (a) 8
- (b) 16
- (c) 9
- (d)18
- **Q.9** Let x(t) be a periodic signal with fundamental period T and Fourier series coefficients a_K . The Fourier series coefficient of $Re\{x(t)\}$ (Where Re (.) denotes the real part of the signal) is
 - (a) $\frac{a_K + a_{-K}^*}{2}$ (b) $\frac{a_K a_{-K}^*}{2}$
 - (c) $\frac{a_K^* + a_{-K}}{2}$ (d) $\frac{a_K^* a_K^*}{2}$
- Q.10 The transfer function of a causal discrete

time system is $H(z) = \frac{z}{z - 0.2}$. Then the

impulse response will be

- (a) stable with ROC : |z| < 0.2
- (b) unstable with ROC : |z| > 0.2
- (c) stable with ROC : |z| > 0.2
- (d) None of these

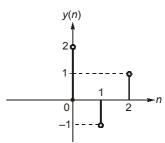
Q. No. 11 to Q. No. 30 carry 2 marks each

Q.11 Consider $y(t) = e^{-t}u(t) * \sum_{k=-\infty}^{\infty} \delta(t-2k)$, if y(t)

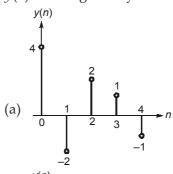
= Ae^{-t} for $0 \le t \le 2$, then value of A is

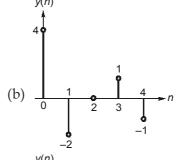
- (b) $\frac{1}{1-a^{-2}}$
- (c) $\frac{1}{1-e^{-3}}$ (d) $\frac{1-e}{1-e^{-2}}$

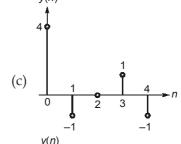
Q.12 Consider a discrete-time system which is both linear and time invariant. For an input $x(n) = \delta(n)$, the output y(n) is given by,

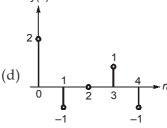


If $x[n] = 2\delta[n] - \delta[n - 2]$, then the output y(n) can be given by









Q.13 If f(t) is a real even continuous time signal, then its Fourier transform will be

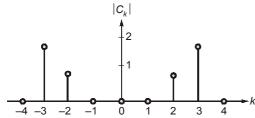
- (a) $\int f(t)\cos(2\omega t)dt$
- (b) $2\int f(t)\cos(\omega t)dt$
- (c) $\int f(t)\sin(\omega t)dt$
- (d) $2\int_{0}^{\infty} f(t)\sin(\omega t)dt$
- **Q.14** The inverse Laplace transform of the signal $X(s) = \log(s + 2) - \log(s + 3)$. Then x(t) is equal to

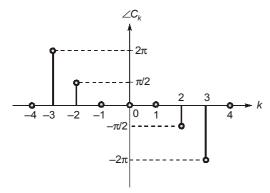
(Assume all initial conditions are zero).

(a)
$$\left(\frac{e^{3t}-e^{-2t}}{t}\right)u(t)$$
 (b) $\left(\frac{e^{-3t}-e^{-2t}}{t}\right)u(t)$

(c)
$$\left(\frac{e^{-3t}-e^{2t}}{t}\right)u(t)$$
 (d) $\left(\frac{e^{3t}-e^{2t}}{t}\right)u(t)$

Q.15 A time domain signal x(t) is represented by the following exponential Fourier series spectra (magnitude and phase).





The corresponding signal x(t) can be given by

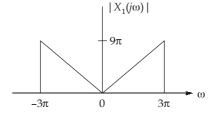
- (Assume that, $\omega_0 = \pi$)
- (a) $4\cos 3\pi t 2\sin 2\pi t$
- (b) $4\sin 3\pi t + 2\cos 2\pi t$
- (c) $4\sin 3\pi t 2\cos 2\pi t$
- (d) $4\cos 3\pi t + 2\sin 2\pi t$
- **Q.16** Suppose that the system *F* takes the Fourier transform of the input, as shown in below figure.

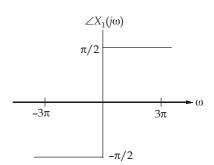
$$x(t)$$
 $y(t) = 2\pi X(-\omega) \mid_{\omega = t}$

Then the output signal $y_3(t)$ of the system shown in the figure below is

$$x(t)$$
 F F F $Y_3(t)$

- (a) $(2\pi)^3 X(t)$ (b) $(2\pi)^3 X(-t)$
- (c) $(2\pi)^4 X(t)$
- (d) $(2\pi)^4 X(-t)$
- **Q.17** A signal $x_1(t)$ whose fourier transform is $X_1(j\omega)$ has the following magnitude and phase response as shown below:





Then determine the signal x(t).

(a)
$$\frac{3}{\pi t}(\cos 3\pi t - \sin 3\pi t)$$

(b)
$$\frac{3}{\pi t}(\pi t \cos 3\pi t - \sin 3\pi t)$$

(c)
$$\frac{3}{\pi t^2} (3\pi t \cos 3\pi t - \sin 3\pi t)$$

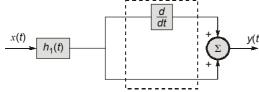
$$(d) \frac{3}{\pi^2 t^2} (3t \cos 3\pi t - \sin 3\pi t)$$

5

Q.18 The Laplace transform of a signal given below is

$$x(t) = \begin{cases} \cos(\pi t); & 0 < t < 1 \\ 0; & \text{otherwise} \end{cases}$$

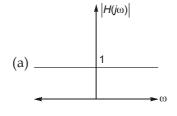
- (a) $\frac{1 e^{-s}}{s^2 + \pi^2}$ (b) $\frac{1 e^{-\pi s}}{s^2 + \pi^2}$
- (c) $\frac{s[1+e^{-s}]}{s^2+\pi^2}$ (d) $\frac{s[1-e^{-s}]}{s^2+\pi^2}$
- Q.19 Consider the system shown below

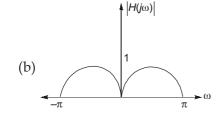


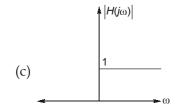
If $h_1(t) = e^{-t} u(t)$, then the impulse response of the entire system is

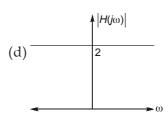
- (a) $e^{-t} u(t)$
- (b) $2e^{-t}u(t) + \delta(t)$
- (c) δ (t)
- (d) None of these
- Q.20 The magnitude plot of the Fourier transform

of the signal
$$H(j\omega) = \frac{1 + 2e^{-j\omega}}{1 + \frac{1}{2e^{-j\omega}}}$$
 is









Q.21 The discrete time signal x[n] has Fourier transform of $X(e^{j\omega}) = \frac{\sin \frac{3\omega}{2}}{\sin \frac{\omega}{2}}$. Then the

value of
$$\frac{1}{\pi} \left| \int_{-\pi}^{\pi} \frac{d}{d\omega} \left[X(e^{j\omega}) \right] \right|^2 d\omega$$
 is

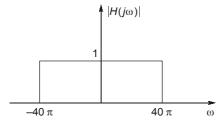
- (a) 4
- (c) 8
- (d) 12
- Q.22 An ideal phase shifter is defined by the frequency response

$$H(\omega) = \begin{cases} -2j; & \omega > 0 \\ 2j; & \omega < 0 \end{cases}$$

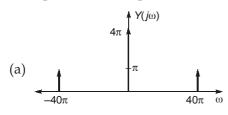
The impulse response of the above phase shifter is

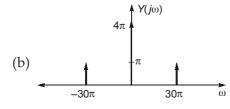
- (a) πt
- (c) $\frac{(\pi t)^{-1}}{2}$ (d) $2(\pi t)^{-1}$
- Q.23 The discrete Fourier transform [DFT] of a discrete sequence x[n] is $X[k] = \{6, 7, 8, 9\}$. If the DFT of the sequence $g[n] = x[n-2]_{\text{mod N}}$ is G[k], then G[1] is
 - (a) 7
- (b) -7
- (c) 9
- (d) -9
- **Q.24** Let x[n] be a real periodic sequence with fundamental period N_0 and Fourier series coefficients $C_k = a_k + jb_k$, where a_k and b_k both are real. If N_0 is even, then $C_{N_0/2}$ is
 - (a) purely real
 - (b) purely imaginary
 - (c) complex
 - (d) none

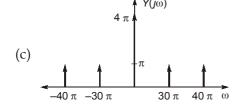
Q.25 A continuous time signal x(t) is defined as $x(t) = 2 + \cos(50\pi t)$ is sampled with sampling interval $t_s = 0.025$ sec and passed through an ideal low pass filter whose frequency response is as shown in figure below

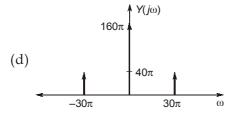


The spectrum of output will be









Q.26 The output y[n] of a discrete time LTI system is found to be $2\left(\frac{1}{3}\right)^n u[n]$ when input x[n] is u[n]. The output y[n] is $\left| k_1 \left(\frac{1}{2} \right)^n + k_2 \left(\frac{1}{3} \right)^n \right| u[n]$ when input is $\left(\frac{1}{2}\right)^n u[n]$. The value of $k_1 + k_2$ is

Q.27 A real signal x[n] with its Fourier transform $X(e^{j\omega})$ has following properties.

(i)
$$x[n] = 0$$
 for $n > 0$

(ii) x[0] is non negative

(iii)
$$Im(X(e^{j\omega})) = \sin(\omega) - \sin(2\omega)$$

(iv)
$$\frac{1}{2} \int_{-\pi}^{\pi} \left| X(e^{j\omega}) \right|^2 d\omega = 3$$

The signal x[n] is

(a)
$$2\delta[n] - \delta[n+1] - \delta[n+3]$$

(b)
$$\delta[n] + \delta[n + 1] - \delta[n + 2]$$

(c)
$$\delta[n + 1] + \delta[n] + \delta[n - 3]$$

$$(d)3\delta[n] + 2\delta[n + 1]$$

Q.28 A discrete time system with input x[n] and output y[n] is described by the relation

$$Y(e^{j\omega}) = e^{-j\omega}X(e^{j\omega}) + \frac{dX(e^{j\omega})}{d\omega}$$

The response of the system for input x[n] = $\delta[n]$ is

(a)
$$\frac{\sin \pi (n-1)}{\pi (n-1)}$$
 (b) $\delta[n-1] + 2\delta[n-1]$

(b)
$$\delta[n-1] + 2\delta[n-1]$$

(c)
$$u[n-1] + \delta[n]$$
 (d) $r[n-1] + u[n]$

(d)
$$r[n-1] + u[n]$$

Q.29 Consider a causal LTI system with frequency

response $H(j\omega) = \frac{1}{3+j\omega}$ for a particular input x(t), this system is observed to produce the output as $y(t) = e^{-3t} u(t) - e^{-4t}$ u(t). Then the input x(t) is

(a)
$$e^{-3t} u(t)$$

(b)
$$e^{-t} u(t)$$

(c)
$$e^{-4t} u(t)$$

(d)
$$e^{4t} u(t)$$

Q.30 Consider the *z*-transform:

$$X(z) = \frac{1}{1 - 2.5z^{-1} + z^{-2}}$$
, it is found to be $X(z)$

is causal signal. Then the value of x[n] at n =0 is



Delhi | Bhopal | Hyderabad | Jaipur | Pune | Kolkata

Web: www.madeeasy.in | **E-mail:** info@madeeasy.in | **Ph:** 011-45124612

SIGNAL & SYSTEM

EC-EE

Date of Test: 10/06/2024

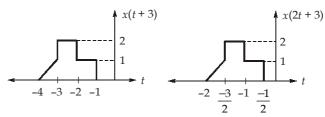
ANSWER KEY >

1.	(c)	7.	(c)	13.	(b)	19.	(c)	25.	(d)
2.	(b)	8.	(a)	14.	(b)	20.	(d)	26.	(b)
3.	(a)	9.	(a)	15.	(d)	21.	(a)	27.	(b)
4.	(c)	10.	(c)	16.	(c)	22.	(d)	28.	(a)
5.	(c)	11.	(b)	17.	(c)	23.	(b)	29.	(c)
6.	(b)	12.	(b)	18.	(c)	24.	(a)	30.	(b)

DETAILED EXPLANATIONS

1. (c)

The signal x(2t + 3) can be obtained by first shifting x(t) to the left by 3 units and then scaling by 2 units



2. (b)

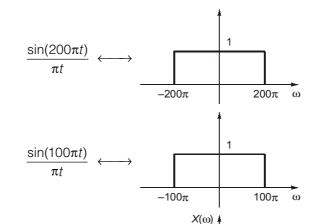
$$e^{-(2t-2)} u(t-1) = e^{-2(t-1)} u(t-1)$$

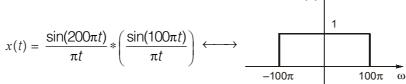
Now,

$$e^{-2t} u(t) \leftrightarrow \frac{1}{2+j\omega}$$

$$e^{-2(t-1)} u(t-1) \leftrightarrow \frac{e^{-j\omega}}{2+j\omega}$$

3. (a)





$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega = \frac{1}{2\pi} \int_{-100\pi}^{100\pi} (1) d\omega = \frac{200\pi}{2\pi} = 100$$

4. (c)

Given

$$x(n) \stackrel{z}{\longleftrightarrow} X(z)$$

by the definition of z-transform,

$$X(z) = \sum_{n = -\infty}^{\infty} x(n)z^{-n}$$

EC EE

The term $\delta[n - 5k]$ is equal 1 if n = 5k and equal to zero otherwise.

$$X(z) = \sum_{k=0}^{\infty} a^k z^{-5k} \qquad [\because n = 5k]$$

$$= \frac{1}{1 - az^{-5}}$$
or
$$X(z) = \frac{z^5}{z^5 - a}$$

$$(1 + \cos 300\pi t)^2 \rightarrow f_{1\,\text{max}} = 300\,\text{Hz}$$

 $(\sin 4000\pi t)^2 \rightarrow f_{2\,\text{max}} = 4000\,\text{Hz}$
 $f_{\text{max}} = f_{1\,\text{max}} + f_{2\,\text{max}} = 4300\,\text{Hz}$
 $f_{s} = 2f_{\text{max}} = 8.6\,\text{kHz}$

6. (b)

Given,
$$x(t) = \frac{\sin(10\pi t)}{\pi t}$$

Taking Fourier transform

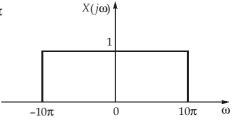
$$X(j\omega) = \begin{cases} 1 ; & |\omega| \le 10\pi \\ 0 ; & |\omega| > 10\pi \end{cases}$$

or

:. The maximum frequency ' ω_m ' present in x(t) is $\omega_m = 10\pi$ Hence we require,







7. (c)

Conjugate anti-symmetric part of x[n] is $\frac{x[n]-x^*[-n]}{2}$.

$$x^*[-n] = [2, 1+j, -2+j5]$$

$$\therefore \frac{x[n] - x^*[-n]}{2} = \frac{[-2 - j5, 1 - j, 2] - [2, (1 + j), -2 + j5]}{2} = [-2 - j2.5, -j, 2 - j2.5]$$

$$X(e^{j\omega}) = e^{j\omega} + e^{-j\omega} + 2(e^{2j\omega} - e^{-2j\omega}) + 3(e^{3j\omega} + e^{-3j\omega})$$

$$= 2\cos\omega + 4j\sin(2\omega) + 2\cos3\omega = 2\cos(\pi) + 4j\sin(2\pi) + 6\cos(3\pi)$$

$$= -2 + 0 - 6 = -8$$

$$|Xe^{j\pi}| = 8$$

9. (a)

$$Re \{x(t)\} = \frac{x(t) + x^*(t)}{2}$$

 \therefore The Fourier coefficient of $x^*(t)$ are

$$b_K = \frac{1}{T} \int_T x^*(t) e^{-jK\frac{2\pi}{T}t} dt$$

Taking conjugate on both sides

$$b_K^* = \frac{1}{T} \int_T x(t) e^{-j(-K)\frac{2\pi}{T}t} dt$$

 $\therefore \qquad \qquad a_{-K} = b_{K}^{*}$

∴ Fourier series Coefficient of $Re \{x (t)\} = \frac{a_K + a_{-K}^*}{2}$

10. (c)

Given,
$$H(z) = \frac{z}{z - 0.2} = \frac{1}{1 - 0.2z^{-1}} \quad \text{ROC:} |z| > 0.2$$

Since the ROC : |z| > 0.2, which includes unit circle.

:. The impulse response will be stable.

11. (b)

Given,
$$y(t) = e^{-t} u(t) * \sum_{k=-\infty}^{\infty} \delta(t-2k)$$

$$= e^{-t} u(t) * (..... + \delta(t+4) + \delta(t+2) + \delta(t) + \delta(t-2) + \delta(t-4) +)$$

Using convolution property of impulse response,

i.e.,
$$x(t) * \delta(t-t_0) = x(t-t_0)$$

$$y(t) = ... + e^{-(t+4)}u(t+4) + e^{-(t+2)}u(t+2) + e^{-t}u(t) + e^{-(t-2)}u(t-2) + e^{-(t-4)}u(t-4)$$

+ ...

In the range $0 \le t < 2$, we may write y(t) as,

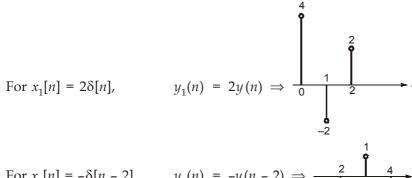
$$\begin{split} y(t) &= \left[\ldots + e^{-(t+4)} \, u(t+4) + e^{-(t+2)} \, u(t+2) + e^{-t} \, u(t) + e^{-(t-2)} \, u(t-2) + e^{-(t-4)} \, u(t-4) + \ldots \right] \, (u(t) - u(t-2)) \\ &= \left(e^{-t} + e^{-(t+2)} + e^{-(t+4)} + \ldots \right) \, ; \quad 0 \leq t < 2 \\ &= e^{-t} \left(1 + e^{-2} + e^{-4} + \ldots \right) \, ; \quad 0 \leq t < 2 \\ &= e^{-t} \left[\frac{1}{1 - e^{-2}} \right] \, ; \quad 0 \leq t < 2 \end{split}$$

$$y(t) = Ae^{-t} \text{ for } 0 \le t < 2$$

$$A = \frac{1}{1 - e^{-2}}$$

(b)

12.



For
$$x_2[n] = -\delta[n-2]$$
, $y_2(n) = -y(n-2) \Rightarrow \frac{2 + \frac{1}{3} + n}{-2}$

$$y(n) = y_1(n) + y_2(n) \Rightarrow \frac{1}{0 + \frac{1}{2} + \frac{1}{3} + n}$$

13. (b)

$$F(\omega) = \int_{-\infty}^{\infty} f(t)e^{-j\omega t} dt$$

$$= \int_{-\infty}^{\infty} [f(t)\cos\omega t - jf(t)\sin\omega t] dt$$

$$= \int_{-\infty}^{\infty} f(t)\cos\omega t dt - j\int_{-\infty}^{\infty} f(t)\sin\omega t dt$$

$$f(t) \Rightarrow \text{even signal}$$

 $f(t) \cos \omega t \Rightarrow \text{even signal}$

 $f(t) \sin \omega t \Rightarrow \text{odd signal}$

$$\int_{-\infty}^{\infty} f(t)\sin\omega t \, dt = 0$$

$$\int_{-\infty}^{\infty} f(t)\cos\omega t \, dt = 2\int_{0}^{\infty} f(t)\cos\omega t \, dt$$

$$F(\omega) = 2\int_{0}^{\infty} f(t)\cos\omega t \, dt$$

14. (b)

:.

Given, $X(s) = \log(s + 2) - \log(s + 3)$

Differentiating both the sides with respect to s

$$\frac{d}{ds}X(s) = \frac{1}{s+2} - \frac{1}{s+3}$$
 ...(i)

From the properties of Laplace transform, we know that,

$$tx(t)\longleftrightarrow -\frac{d}{ds}X(s)$$

Thus equation (i) can be written as,

$$-tx(t) = [e^{-2t} - e^{-3t}]u(t)$$

or,

$$x(t) = \left[\frac{e^{-3t} - e^{-2t}}{t}\right] u(t)$$

15. (d)

$$C_k = j\delta(k+2) - j\delta(k-2) + 2\delta(k+3) + 2\delta(k-3)$$

$$x(t) = \sum_{k=-\infty}^{\infty} C_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{\infty} C_k e^{jk\pi t}$$

$$= je^{-j2\pi t} - je^{j2\pi t} + 2e^{-j3\pi t} + 2e^{j3\pi t}$$

$$= 4\cos(3\pi t) + 2\sin(2\pi t)$$

16. (c)

Given that,

Let,

$$y_1(t) = 2\pi X(-\omega)|_{\omega = t}$$

We have,

$$y_1(t) = 2\pi \int_{-\infty}^{\infty} x(u)e^{jut}du$$

Similarly, let $y_2(t)$ be the output due to passing x(t) through 'F' twice.

$$y_2(t) = 2\pi \int_{v=-\infty}^{\infty} 2\pi \int_{u=-\infty}^{\infty} x(u)e^{juv} du e^{jt v} dv$$

$$= (2\pi)^2 \int_{u=-\infty}^{\infty} x(u) \int_{v=-\infty}^{\infty} e^{j(t+u)v} dv du$$

$$= (2\pi)^2 \int_{u=-\infty}^{\infty} x(u)(2\pi)\delta(t+u)du$$

$$= (2\pi)^3 X(-t)$$

Finally, let $y_3(t)$ be the output due to passing x(t) through F three times

$$y_3(t) = 2\pi \int_{u=-\infty}^{\infty} (2\pi)^3 x(-u)e^{jtu} du$$

$$= (2\pi)^4 \int_{-\infty}^{\infty} e^{-jtu} x(u) du = (2\pi)^4 X(t)$$

17. (c)

The fourier transform of x(t) can be written

$$X_1(j\omega) = |X_1(j\omega)|e^{j\angle X_1(j\omega)}$$

Let,

$$X_{1a}(j\omega) = \begin{cases} 1; & |\omega| < 3\pi \\ 0; & \text{otherwise} \end{cases}$$

Note that, given $X_1(j\omega)$ is "3jw" times $X_{1a}(j\omega)$

$$X_1(j\omega) = \begin{cases} 3j\omega; & |\omega| < 3\pi \\ 0; & \text{otherwise} \end{cases}$$

Since, at

$$\omega = 3\pi$$
, $|X_1(j\omega)| = 9\pi$ and $\angle X_1(j\omega) = \frac{\pi}{2}$

$$\omega = -3\pi$$
, $|X_1(j\omega)| = 9\pi$ and $\angle X_1(j\omega) = -\frac{\pi}{2}$

By taking inverse fourier transform,

Thus,

$$x_1(t) = 3\frac{d}{dt}x_{1a}(t)$$

[By using differential property]

also we can express

$$x_{1a}(t) = \frac{\sin 3\pi t}{\pi t}$$

Thus,

$$x_1(t) = 3 \frac{d}{dt} \left[\frac{\sin 3\pi t}{\pi t} \right]$$
$$= \frac{3}{\pi} \times \frac{1}{t^2} \left[3\pi t \cos 3\pi t - \sin 3\pi t \right]$$

$$x_1(t) = \frac{3}{\pi t^2} \left[3\pi t \cos 3\pi t - \sin 3\pi t \right]$$

18. (c)

We know that the Laplace transform of

$$\cos(at)u(t) = \frac{s}{s^2 + a^2}$$

$$\cos(\pi t)u(t) = \frac{s}{s^2 + \pi^2}$$

now, the given function x(t) can be written as,

$$x(t) = \cos(\pi t)u(t) - \cos \pi t \ u(t-1)$$

$$= \cos(\pi t)u(t) - \cos \pi(t-1+1) \ u(t-1)$$

$$= \cos(\pi t)u(t) - \cos \left[\pi(t-1) + \pi\right] \ u(t-1)$$

$$= \cos \pi \ t u(t) - \left[\cos \pi(t-1) \ (-1) - 0\right] \ u(t-1)$$

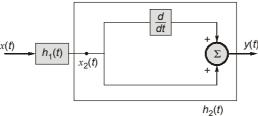
$$= \cos \pi \ t u(t) + \cos \pi(t-1) \ u(t-1)$$

By taking Laplace transform,

$$X(s) = \frac{s}{s^2 + \pi^2} + \frac{s e^{-s}}{s^2 + \pi^2} [\because x(t - t_0) = X(s) \cdot e^{-st_0}, \text{ by shifting property}]$$

$$X(s) = \frac{s[1 + e^{-s}]}{s^2 + \pi^2}$$

19. (c)



Let

$$x_{2}(t) = \delta(t)$$

$$h_{2}(t) = \left(\delta(t) + \frac{d}{dt}\delta(t)\right)$$

$$h_{1}(t) = e^{-t}u(t)$$

$$h(t) = e^{-t}u(t) * \left(\delta(t) + \frac{d}{dt}\delta(t)\right)$$

$$h(t) = e^{-t}u(t) * \delta(t) + e^{-t}u(t) * \frac{d}{dt}\delta(t)$$

$$= e^{-t}u(t) + \frac{d}{dt}(e^{-t}u(t)) * \delta(t)$$

$$= e^{-t}u(t) + \frac{d}{dt}(e^{-t}u(t))$$

$$= e^{-t}u(t) - e^{-t}u(t) + e^{-t}\delta(t)$$

$$h(t) = \delta(t)$$

$$\therefore e^{-t}\delta(t) = e^{0}\delta(t) = \delta(t)$$

20. (d)

$$H(j\omega) = \frac{1+2e^{-j\omega}}{1+\frac{1}{2e^{-j\omega}}} = \frac{1+2e^{-j\omega}}{2e^{-j\omega}+1} \cdot 2e^{-j\omega}$$
$$|H(j\omega)| = 2$$

21. (a)

Given,
$$X(e^{j\omega}) = \frac{\sin\frac{3\omega}{2}}{\sin\frac{\omega}{2}} = \frac{e^{j3\omega/2} - e^{-j3\omega/2}}{e^{j\omega/2} - e^{-j\omega/2}} = \frac{e^{j3\omega/2} \left[1 - e^{-j3\omega}\right]}{e^{j\omega/2} \left[1 - e^{-j\omega}\right]}$$

$$= e^{j\omega} \left[\frac{1 - e^{-j3\omega}}{1 - e^{-j\omega}}\right]$$

$$X(e^{j\omega}) = \frac{e^{j\omega}}{1 - e^{-j\omega}} - \frac{e^{-j2\omega}}{1 - e^{-j\omega}}$$
by taking inverse DTFT,
$$x[n] = u[n+1] - u[n-2]$$

$$= \begin{cases} 1; & -1 \le n < 2 \\ 0; & \text{otherwise} \end{cases}$$

From parseval's theorem,

$$\sum_{n=-\infty}^{\infty} |nx[n]|^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} \left[\frac{d}{d\omega} X(e^{j\omega}) \right]^2 d\omega$$

$$\therefore \frac{1}{\pi} \int_{-\pi}^{\pi} \left[\frac{d}{d\omega} X(e^{j\omega}) \right]^2 d\omega = 2 \sum_{n=-\infty}^{\infty} |nx[n]|^2 d\omega$$

$$= 2 \sum_{n=-1}^{1} |n|^2 = 2[1+0+1] = 4$$

$$\frac{1}{\pi} \int_{-\pi}^{\pi} \left[\frac{d}{d\omega} X(e^{j\omega}) \right]^2 d\omega = 4$$

22. (d)

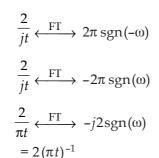
> By redrawing the given frequency response, we get, We can write $H(\omega) = -j2\operatorname{sgn}(\omega)$

We know that,

For

$$\operatorname{sgn}(t) \overset{\operatorname{FT}}{\longleftrightarrow} \frac{2}{j\omega}$$

By duality property



or

23. (b)

$$X[k] = \sum_{n=0}^{N-1} x[n] e^{-j\frac{2\pi}{N}nK}$$

$$g[n] = x[n-2]_{\text{mod N}}$$

$$G[k] = e^{-j\frac{2\pi}{N}(2)k} X[k]$$

$$G[1] = e^{-j\frac{2\pi}{4}(2)1} X[1] = e^{-j\pi} X[1]$$

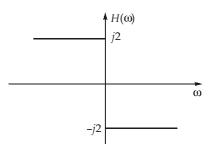
$$G[1] = -X[1] = -7$$

24.

By the definition of Fourier series,

We can write $C_{N_0/2}$ for N_0 is even,

$$C_{N_0/2} = \frac{1}{N_0} \sum_{n=0}^{N-1} x[n] e^{-j\left(\frac{N_0}{2}\right)\left(\frac{2\pi}{N_0}\right)^n}$$



$$= \frac{1}{N_0} \sum_{n=0}^{N-1} x[n] e^{-j\pi n} = \frac{1}{N_0} \sum_{n=0}^{N-1} (-1)^n x[n] = \text{real}$$

25. (d)

Given,
$$x(t) = 2 + \cos(50\pi t)$$

Frequency of signal
$$\omega_{\rm sig} = 50\pi$$

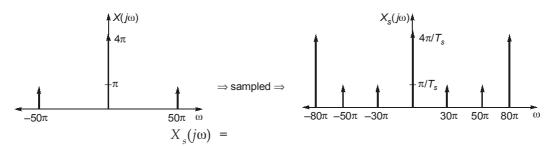
$$\omega_{\text{sig}} = 50\pi$$
 $T_s = 0.025 \text{ sec}$

∴ sampling frequency $\omega_s = \frac{2\pi}{T_c} = 80 \,\pi \,\text{rad/sec}$

then,
$$X(j\omega) = 4\pi\delta(\omega) + \pi[\delta(\omega + 50\pi) + \delta(\omega - 50\pi)]$$

Let the sampled signal be represented as $X_s(j\omega)$, where $X_s(j\omega)$ is given as

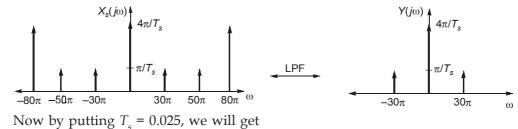
$$X_s(j\omega) = \frac{1}{T_s} \sum_{m=-\infty}^{\infty} X(j(\omega - n\omega_s))$$

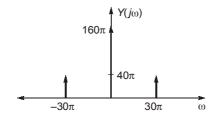


$$40\sum_{m=-\infty}^{\infty} [4\pi\delta(\omega - 80\pi)] + \pi\delta(\omega - 50\pi - 80\pi n) - \pi\delta(\omega + 50\pi - 80\pi n)]$$

now, the sampled input $X_s(j\omega)$ is passed through a low passed filter having cut-off frequency at $\omega = 40\pi$.

Therefore the output $Y(j\omega)$ will contain only the components which are less than $\omega = 40 \pi$.





$$X(z) = \frac{z}{z-1} \qquad |z| > 1$$

$$Y(z) = \frac{2z}{z - \frac{1}{3}}$$
 $|z| > \frac{1}{3}$

$$H(z) = \frac{2(z-1)}{z-\frac{1}{3}}$$
 $|z| > \frac{1}{3}$

$$X'(z) = \frac{z}{z - \frac{1}{2}} \qquad |z| > \frac{1}{2}$$

$$Y'(z) = H(z) \cdot X'(z)$$

$$= \frac{2z(z-1)}{\left(z-\frac{1}{2}\right)\left(z-\frac{1}{3}\right)} \qquad |z| > \frac{1}{2}$$

Taking inverse *z* transform

$$y[n] = \left[-6\left(\frac{1}{2}\right)^n + 8\left(\frac{1}{3}\right)^n \right] u[n]$$

$$k_1 = -6$$
, $k_2 = 8$
so, $k_1 + k_2 = 2$

27. (b) If x[n] is real

$$\operatorname{odd}[x[n]] \xrightarrow{FT} j\operatorname{Im}[X(e^{j\omega})]$$

$$\text{odd}[x[n]] = F^{-1} \left[\frac{1}{2} \left(e^{j\omega} - e^{-j\omega} - e^{2j\omega} + e^{-2j\omega} \right) \right]$$

$$= \frac{1}{2} \left[\delta[n+1] - \delta[n-1] - \delta[n+2] + \delta[n-2] \right]$$

$$\therefore \qquad \text{odd } [x[n]] = \frac{x[n] - x[-n]}{2}$$

Since,
$$x[n] = 0 \text{ for } n > 0$$
$$x[n] = 2 \text{ odd}[x[n]]$$
$$= \delta[n+1] - \delta[n+2] \text{ for } n < 0$$

using parshevel's theorem

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} \left| X(e^{j\omega}) \right|^2 d\omega = \sum_{n=-\infty}^{\infty} \left| x[n] \right|^2$$

$$(x[0])^{2} - 2 = 3$$

$$x[0] = \pm 1$$

$$x[0] > 0$$

$$x[n] = \delta[n] + \delta[n+1] - \delta[n+2]$$

$$x[n] = \delta[n]$$

$$X(e^{j\omega}) = 1$$

$$dX(e^{j\omega})$$

$$\frac{dX(e^{j\omega})}{d\omega} = 0$$

$$\therefore \qquad Y(e^{j\omega}) = e^{-j\omega} X(e^{j\omega})$$

$$h[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{-j\omega} . e^{j\omega n} d\omega = \frac{\sin \pi (n-1)}{\pi (n-1)}$$

29. (c)

Given, the Causal LTI system,

and output,
$$H(j\omega) = \frac{1}{3+j\omega}$$
$$y(t) = e^{-3t} u(t) - e^{-4t} u(t)$$
$$x(t) \xrightarrow{\qquad \qquad } h(t) \xrightarrow{\qquad \qquad } y(t)$$

We know that, $H(j\omega) = \frac{Y(j\omega)}{X(j\omega)}$ $Y(j\omega) = \frac{1}{3+j\omega} - \frac{1}{4+j\omega} = \frac{1}{(3+j\omega)(4+j\omega)}$ $\therefore X(j\omega) = \frac{Y(j\omega)}{H(j\omega)} = \frac{1}{4+j\omega}$

By inverse Fourier transform of $X(j\omega)$, we have,

$$x(t) = e^{-4t} u(t)$$

Given,
$$X(z) = \frac{1}{1 - 2.5z^{-1} + z^{-2}} = \frac{1}{(z^{-1} - 2)(z^{-1} - \frac{1}{2})}$$
$$\frac{1}{(z^{-1} - 2)(z^{-1} - \frac{1}{2})} = \frac{A}{z^{-1} - 2} + \frac{B}{z^{-1} - \frac{1}{2}}$$
$$\therefore A = \frac{1}{2 - \frac{1}{2}} = \frac{1}{3/2} = \frac{2}{3}$$
$$B = \frac{1}{\frac{1}{2} - 2} = -\frac{2}{3}$$

$$X(z) = \frac{\frac{2}{3}}{z^{-1} - 2} + \frac{-\frac{2}{3}}{z^{-1} - \frac{1}{2}}$$
$$= \frac{-\frac{1}{3}}{1 - \frac{1}{2}z^{-1}} + \frac{\frac{4}{3}}{1 - 2z^{-1}}$$

Given X(z) is a causal system, the ROC is right of the right most pole.

hence,
$$x[n] = -\frac{1}{3} \left(\frac{1}{2}\right)^n u[n] + \frac{4}{3} (2)^n u[n]$$

$$x(0) = -\frac{1}{3} + \frac{4}{3} = \frac{3}{3} = 1$$