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INDUCTION

ELECTRICAL ENGINEERING

Date of Test : 29/07/2024

ANSWER KEY >

1. (d)	7. (a)	13. (b)	19. (c)	25. (d)
2. (b)	8. (d)	14. (a)	20. (d)	26. (a)
3. (d)	9. (a)	15. (b)	21. (b)	27. (b)
4. (d)	10. (d)	16. (a)	22. (c)	28. (a)
5. (a)	11. (d)	17. (b)	23. (b)	29. (b)
6. (d)	12. (b)	18. (b)	24. (d)	30. (b)

DETAILED EXPLANATIONS

1. (d)

We know that,

$$\frac{\text{Starting torque}}{\text{Full load torque}} = \frac{T_{st}}{T_{fl}} = x^2 \left(\frac{I_{sc}}{I_{fl}} \right)^2 \times s_{fl}$$

$$\text{or,} \quad 0.4 = x^2 \times (5)^2 \times 0.035$$

$$\text{or,} \quad x^2 = \frac{0.4}{25 \times 0.035}$$

$$x = \sqrt{\frac{0.4}{25 \times 0.035}} = 0.676$$

∴ The percentage of tapping is 67.6%.

2. (b)

$$N_s \text{ (stator field)} = \frac{120 \times 50}{4} = 1500 \text{ rpm;}$$

$$N_s \text{ (rotor field)} = \frac{120 \times 30}{4} = 900 \text{ rpm}$$

$$\therefore N_r = 1500 \pm 900 = 2400 \text{ rpm, } 600 \text{ rpm}$$

3. (d)

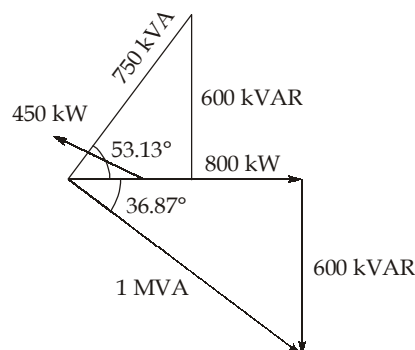
$$\text{Starting winding current } I_s = 3 \angle -15^\circ \text{ A} = (2.9 - j0.78) \text{ A}$$

$$\text{Running winding current } I_m = 5 \angle -40^\circ \text{ A} = (3.83 - j3.21) \text{ A}$$

The component of running winding current that lags behind the supply voltage by 90°
 = Reactive component of running winding current
 = 3.21 A

4. (d)

The given condition can be explained with phasors,



Active power consumed by induction motor,
 = 1 MVA \times 0.8 = 800 kW

Reactive power consumed by induction motor,
 = 800 kW \times $\tan(36.87^\circ)$
 = 600 kVAR

Active power consumed by synchronous condenser,
 = 750 KVA \times 0.6 = 450 kW

Reactive power delivered by synchronous condenser
 $= 450 \text{ kW} \times \tan(53.13^\circ)$
 $= 600 \text{ kVAR}$

$$Q_{\text{net}} = 0 \quad \text{i.e. } \phi = 0^\circ$$

∴ The power factor of the total load is unity

$$\cos \phi = 1$$

5. (a)

The rotor copper loss $= \frac{s}{1-s} \times \text{Gross mechanical power developed}$

$$\text{Synchronous speed, } N_s = \frac{120f}{P} = \frac{120 \times 50}{6} = 1000 \text{ rpm}$$

$$\text{Slip, } s = \frac{N_s - N_r}{N_s} = \frac{1000 - 950}{1000} = 0.05$$

$$\begin{aligned} \text{The rotor copper loss} &= \left(\frac{0.05}{1-0.05} \right) \times (4500 + 850) \\ &= 281.58 \text{ W} \end{aligned}$$

6. (d)

$$\begin{aligned} T_s &= 1.5 T_f \\ T_{\text{max.}} &= 2 T_f \end{aligned}$$

For maximum torque, $s_{mT} = \frac{r_2}{x_2}$

$$\frac{T_s}{T_{\text{max}}} = \frac{1.5T_f}{2T_f} = \frac{2s_{mT}}{1+s_{mT}^2}$$

$$\text{i.e. } 1.5s_{mT}^2 - 4s_{mT} + 1.5 = 0$$

$$\therefore s_{mT} = 0.45$$

7. (a)

The slip at maximum torque is,

$$S_{\text{max},T} = \frac{R_2}{X_2} = \frac{0.02}{0.08} = 0.25$$

$$\text{Synchronous speed, } N_s = \frac{120 \times 50}{8} = 750 \text{ rpm}$$

$$\begin{aligned} \omega_s &= \frac{2\pi}{60} \times N_s = \frac{2\pi}{60} \times 750 \\ &= 78.54 \text{ rad/sec} \end{aligned}$$

$$\text{Stator voltage, } V_1 = \frac{220}{\sqrt{3}} = 127 \text{ V}$$

Maximum torque developed by the motor,

$$T_{\text{max}} = \frac{3V_1^2}{2\omega_s \times X_2} = \frac{3 \times (127)^2}{2 \times 78.54 \times 0.08} = 3850.51 \text{ N-m}$$

8. (d)

$$\text{Synchronous speed, } \omega_s = \frac{2}{P} \times 2\pi f = \frac{4 \times \pi \times 50}{6} = 104.72 \text{ rad/sec}$$

$$\text{Starting torque, } T_{\text{starting}} = \frac{3}{\omega_s} \cdot \frac{E_2^2 r_2'}{(r_2')^2 + (x_2')^2}$$

$$40 = \frac{3}{104.72} \times \frac{E_2^2 \times 0.32}{(0.32)^2 + (3.2)^2}$$

Rotor voltage at standstill,

$$E_2 = 212.43 \text{ V}$$

9. (a)

For same air gap flux, $\frac{V}{f}$ ratio should be constant

$$\text{Flux, } \phi = \frac{V}{f} = \text{constant}$$

$$\frac{V_2}{f_2} = \frac{V_1}{f_1}$$

$$V_2 = \frac{400}{50} \times 30 = 240 \text{ V}$$

Synchronous speed of motor for 50 Hz source

$$N_s = \frac{120 \times 50}{4} = 1500 \text{ rpm}$$

$$\text{Slip, } s_1 = \frac{1500 - 1440}{1500} = 0.04$$

At small value of slip, the electromagnetic torque is given by

$$T = \frac{3}{\omega_s} \times \frac{V^2 s}{r_2}$$

$$T \propto \frac{V^2}{f} \cdot s$$

$$\text{For same torque, } \frac{V_2^2}{f_2} \cdot s_2 = \frac{V_1^2}{f_1} \cdot s_1$$

$$\frac{(240)^2}{30} s_2 = \frac{400^2}{50} \times 0.04$$

$$\text{Slip, } s_2 = 0.067$$

Synchronous speed of motor at 30 Hz source,

$$N_{s2} = \frac{120 \times 30}{4} = 900 \text{ rpm}$$

$$\text{Rotor speed, } N = (1 - 0.067) \times 900$$

$$N = 840 \text{ rpm}$$

10. (d)

Ratio of full load torque to maximum torque is given by

$$\frac{T_{fl}}{T_m} = \frac{2}{\frac{s_m}{s} + \frac{s}{s_m}}$$

Slip at maximum torque,

$$s_m = \frac{R_2}{X_2} = \frac{0.25}{4} = 0.0625 \Omega$$

Slip at full load torque, $s_{fl} = \frac{1500 - 1440}{1500} = 0.04$

Now,
$$\frac{T_{fl}}{T_m} = \frac{2}{\frac{0.0625}{0.04} + \frac{0.04}{0.0625}}$$

So,
$$\frac{T_m}{T_{fl}} = 1.10125$$

11. (d)

Given, Pole, $P = 6$

$$f = 50 \text{ Hz}$$

Synchronous speed,
$$N_s = \frac{120f}{P} = \frac{120 \times 50}{6} = 1000 \text{ rpm}$$

Slip,
$$s = \frac{1000 - 960}{1000} = 0.04$$

Mechanical power developed

$$P_{\text{mech}} = 20000 + 1100 = 21100 \text{ W}$$

$$\text{Rotor copper loss} = \frac{s}{1-s} \times \text{mechanical power developed}$$

$$= \frac{0.04}{(1-0.04)} \times 21100 \quad \dots(i)$$

$$\text{Also rotor copper loss} = 3I_2^2 \times R_2 + 300$$

$$= 3 \times (40)^2 \times R_2 + 300 \quad \dots(ii)$$

From equation (i) and (ii), we get

$$4800 \times R_2 + 300 = \frac{0.04}{(1-0.04)} \times 21100$$

$$4800 R_2 = 579.17$$

$$R_2 = 0.121 \Omega$$

12. (b)

Electromagnetic torque for induction motor is given by,

$$T = \frac{3}{\omega_s} \cdot \frac{V^2 (R'_2 / s)}{\left(\frac{R'_2}{s}\right)^2 + (X'_2)^2}$$

At starting, $s = 1$

$$T = \frac{3}{\omega_s} \cdot \frac{V^2 R'_2}{(R'_2)^2 + (X'_2)^2}$$

and

$$T \propto V^2$$

$$\frac{T_2}{T_1} = \frac{V_2^2}{V_1^2}$$

$$\frac{45}{60} = \frac{V_2^2}{(400)^2}$$

$$V_2 = \sqrt{\frac{400^2 \times 45}{60}} = 346.41 \text{ V}$$

13. (b)

For small slips, torque is

$$T_e \propto \frac{sV^2}{R_2 f}$$

$$\text{Slip, } s_1 = \frac{N_s - N_1}{N_s} = \frac{750 - 720}{750} = 0.04$$

$$\text{Slip, } s_2 = \frac{750 - 690}{750} = 0.08$$

For constant torque,

$$\frac{s_1}{(R'_2)_{\text{old}}} = \frac{s_2}{(R'_2)_{\text{new}}}$$

$$(R'_2)_{\text{new}} = \frac{0.05 \times 0.08}{0.04}$$

$$(R'_2)_{\text{new}} = 0.1$$

$$R_{\text{ext}} = 0.1 - 0.05 \\ = 0.05 \Omega$$

14. (a)

Ratio of full load torque to maximum torque is given by

$$\frac{T}{T_{\text{max}}} = \frac{2}{\frac{s_m}{s} + \frac{s}{s_m}}$$

$$\frac{1}{4} = \frac{2}{\frac{0.25}{s} + \frac{s}{0.25}}$$

$$s^2 - 2s + 0.0625 = 0$$

$$\text{Slip, } s = 0.03175$$

As rotational losses are neglected

$$P_{\text{shaft}} = P_{\text{developed}}$$

$$\text{Copper loss} = \frac{(P_{\text{dev}}) \times s}{1 - s}$$

$$\text{Copper loss} = \frac{50000 \times 0.03175}{(1 - 0.03175)}$$

$$\text{Copper loss} = 1639.55 \text{ W}$$

15. (b)

At starting slip, $s = 1$

$$I = \frac{V}{\sqrt{R_2^2 + X_2^2}}$$

and $(X_2)_{50 \text{ Hz}} = X_2$
 $(X_2)_{25 \text{ Hz}} = 0.5 X_2$

$$\text{Current, } (I)_{50 \text{ Hz}} = \frac{V}{X_2 \sqrt{\left(\frac{R_2}{X_2}\right)^2 + 1}}$$

and $\text{Current, } (I)_{25 \text{ Hz}} = \frac{V}{X_2 \sqrt{\left(\frac{R_2}{X_2}\right)^2 + 0.25}}$

$$\frac{(I)_{25 \text{ Hz}}}{(I)_{50 \text{ Hz}}} = \frac{\sqrt{s_m^2 + 1}}{\sqrt{s_m^2 + 0.25}} \quad \left(\text{Given, } s_m = \frac{R_2}{X_2} = 0.4 \right)$$

$$\frac{(I)_{25 \text{ Hz}}}{(I)_{50 \text{ Hz}}} = \frac{\sqrt{0.4^2 + 1}}{\sqrt{0.4^2 + 0.25}} = 1.68$$

16. (a)

$$P_{\text{shaft}} = 25000 \text{ W}$$

$$P_{\text{dev}} = P_{\text{shaft}} + \text{Rotational loss} \\ = 25000 + 350$$

$$P_{\text{dev}} = 25350 \text{ W}$$

$$P_{\text{ag}} = \frac{25350}{1 - 0.04} = 26406.25 \text{ W}$$

$$P_{\text{in}} = P_{\text{ag}} + \text{stator loss} \\ = 26406.25 + 1500 + 800$$

$$P_{\text{in}} = 28706.25 \text{ W}$$

$$\text{Efficiency} = \frac{P_{\text{out}}}{P_{\text{in}}} \times 100 = \frac{25000}{28706.25} \times 100$$

$$\% \eta = 87.09\%$$

17. (b)

$$\text{Synchronous speed, } N_s = \frac{120 f_1}{P} = \frac{120 \times 50}{6} = 1000 \text{ rpm}$$

$$\text{Slip, } s = \frac{f_2}{f_1} = \frac{1.5}{50} = 0.03 \text{ or } 3\%$$

$$\text{Rotor speed, } N_r = (1 - s) N_s = (1 - 0.03) \times 1000 = 970 \text{ rpm}$$

$$\omega_r = \frac{2\pi N_r}{60} = \frac{2\pi \times 970}{60} = 101.58 \text{ mechanical rad/sec}$$

$$\begin{aligned} \text{Shaft power output } P &= T \omega_r \\ &= 150 \times 101.58 = 15236 \text{ W} = 15.24 \text{ kW} \end{aligned}$$

18. (b)

The mmf distribution contains a fundamental and a family of space harmonics of order $h = 6m \pm 1$, where m is positive number.

In a three phase machine, when sinusoidally varying currents flow through the winding, the space harmonic wave rotate at $(1/h)$ times the speed of the fundamental wave. The space harmonic waves rotate in the same direction as the fundamental wave if $h = 6m \pm 1$ and in the opposite direction if $h = 6m - 1$.

19. (c)

In order to avoid saturation in stator and rotor cores which would cause sharp increase in magnetizing current, the flux ϕ_r must be kept constant as ' f ' is varied. To achieve this when ' f ' is

varied, ' V ' must also be varied such that $\left(\frac{V}{f}\right)$ remains constant.

20. (d)

Given, motor is at standstill. The respective induced emf in stator and rotor will be

$$E_1 = \sqrt{2}\pi f_1 K_{w1} N_1 \phi$$

$$E_2 = \sqrt{2}\pi f_2 K_{w2} N_2 \phi$$

After taking ratio,

$$\frac{E_1}{E_2} = \frac{K_{w1} N_1}{K_{w2} N_2} = \frac{N_1'}{N_2'} \quad (\text{as } f_1 = f_2 \text{ at stand still})$$

Where,

N_1' = Effective stator turns per phase

N_2' = Effective rotor turns per phase

N_1 = Stator turns per phase

N_2 = Rotor turns per phase

Thus,

$$\frac{5 \times 4}{K_{w2}} = 2$$

\therefore

$$K_{w2} = \frac{5 \times 4}{2} = 10$$

21. (b)

$$\text{Synchronous speed, } N_s = \frac{120 \times 50}{6} = 1000 \text{ rpm}$$

$$\text{Stalling speed} = 900 \text{ rpm}$$

$$\text{Slip at stalling torque, } s = \frac{1000 - 900}{1000} = 0.1$$

$$\text{Slip at maximum torque; } S_{mT} = \frac{R_2}{X_2} = \frac{0.01}{X_2}$$

$$\therefore 0.1 = \frac{0.01}{X_2}$$

$$X_2 = 0.1 \Omega$$

To obtain maximum torque at starting,

Let rotor resistance = R_2'

at starting, $s = 1$

$$S_{mT} = \frac{R_2'}{X_2}$$

$$\Rightarrow 1 = \frac{R_2'}{0.1}$$

$$\Rightarrow R_2' = 0.1 \text{ } \Omega/\text{phase}$$

The external resistance to be added,

$$R_{\text{ext}} = 0.1 - 0.01 \\ = 0.09 \text{ } \Omega/\text{phase}$$

22. (c)

For $f_2 = 15 \text{ Hz}$, the slip is

$$s = \pm \frac{f_2}{f_1} = \pm \frac{15}{60} = \pm \frac{1}{4}$$

$$\text{The synchronous speed, } N_s = \frac{120 \times f}{P} = \frac{120 \times 60}{6} = 1200 \text{ rpm}$$

The speed of the system for $f_2 = 15 \text{ Hz}$

$$N_r = (1 \pm s)N_s = (1 \pm 0.25)1200 \\ = 900 \text{ and } 1500 \text{ rpm}$$

\therefore hence option (c) is correct.

We can check for $f_2 = 120 \text{ Hz}$

$$s = \pm \frac{120}{60} = \pm 2$$

$$N_r = (1 \pm 2) 1200 \\ = -1200 \text{ and } 3600 \text{ rpm}$$

23. (b)

$$\text{Full load shaft power} = 15 \times 746 = 11190 \text{ W}$$

$$\text{Mechanical power developed} = 11190 + 750 = 11940 \text{ W}$$

$$\text{Air gap power} = \frac{\text{Mechanical power developed}}{1 - s}$$

$$\text{Slip, } s = \frac{N_s - N_r}{N_s}$$

$$N_s = \frac{120f}{P} = \frac{120 \times 60}{4} = 1800 \text{ rpm}$$

$$s = \frac{1800 - 1728}{1800} = 0.04$$

$$P_{ag} = \frac{11940}{1 - 0.04} = 12437.5 \text{ W}$$

$$\text{Rotor copper loss} = sP_{ag} = 0.04 \times 12437.5 \\ = 497.5 \text{ W}$$

24. (d)

We know, $P_{Cu} = sP_g$... (copper loss in terms of air gap power)

$$\Rightarrow P_g = \frac{P_{Cu}}{s} = \frac{300}{0.04} = 7500 \text{ W}$$

$$\text{Now } P_m = P_g(1 - s) = 7500(1 - 0.04) = 7200 \text{ W}$$

$$\text{Here synchronous speed, } N_s = \frac{120f}{P} = \frac{120 \times 50}{4} = 1500 \text{ rpm}$$

$$\text{Torque developed} = \frac{P_g}{\omega_s} = \frac{7500}{2\pi \times \frac{1500}{60}} = 47.75 \text{ N-m}$$

Alternatively, torque can be calculated as

$$T = \frac{P_m}{\omega_s(1 - s)} = \frac{7200}{2\pi \times \frac{1500}{60}(1 - 0.04)} = 47.75 \text{ N-m}$$

25. (d)

$$\frac{T_{st}}{T_{fl}} = \left(\frac{I_{st}}{I_{fl}} \right)^2 s_{fl}$$

For

$$T_{st} = T_{fl}$$

$$\frac{I_{st}}{I_{fl}} = \sqrt{\frac{1}{s_{fl}}} = \frac{1}{\sqrt{0.01}} = 10$$

26. (a)

$$\text{Power output, } P_0 = 10 \text{ kW}$$

$$\text{Frequency, } f = 50 \text{ Hz}$$

$$\text{Poles, } P = 6$$

$$\text{Slip, } S = 0.04$$

$$\text{Friction and windage losses} = 0.4 \text{ kW}$$

$$\text{Mechanical power developed} = 10.4 \text{ kW}$$

$$\text{Air gap power, } P_g = \frac{\text{Mechanical power developed}}{1 - s} = \frac{10.4}{1 - 0.04} = 10.83 \text{ kW}$$

$$\text{Synchronous speed} = \frac{120 \times 50}{6} = 1000 \text{ rpm or } 104.72 \text{ rad/sec}$$

Full load electromagnetic torque,

$$T_e = \frac{P_g}{\omega_s} = \frac{10.83 \times 10^3}{104.72} = 103.42 \text{ N-m}$$

27. (b)

Given,

$$I_{st} = 6 \times I_{fL}$$

$$I_{fL} = \frac{\text{Power in kVA}}{\sqrt{3} \times V_L} = \frac{50 \times 10^3}{\sqrt{3} \times 440} = 65.608 \text{ A}$$

Current drawn by auto transformer from the mains at starting,

$$\begin{aligned} I_{st} &= x^2 I_{st(\text{motor})} = x^2 \times 6 \times I_{fl} \\ &= (0.5)^2 \times 6 \times 65.608 \\ &= 98.412 \text{ A} \end{aligned}$$

Starting kVA drawn by the auto transformer

$$\begin{aligned} &= \sqrt{3} V_L I_{st(\text{auto})} \\ &= \sqrt{3} \times 440 \times 98.412 \\ &= 75 \text{ kVA} \end{aligned}$$

28. (a)

We know that,

$$\text{Torque, } T = \frac{3}{\omega_{sm}} \times \frac{V^2}{R_2'} s \text{ (for low slip)}$$

Now, $T = \text{constant}$ $T \propto V^2 s$

(or) $V_2^2 s_2 = V_1^2 s_1$

(or) $s_2 = \left(\frac{V_1}{V_2}\right)^2 s_1$

(or) $s_2 = 4s_1$,

hence slip increases 4 times,

Also, $T = \frac{3I_2'^2}{\omega_{sm}} \times \frac{R_2'}{s} = \text{const.}$

(or) $I_2'^2 \propto s$

$$\frac{I_2'}{I_1} = \sqrt{\frac{s_2}{s_1}} = \sqrt{\frac{4}{1}} = 2$$

Hence, current increases by 2 times.

29. (b)

$$\text{Synchronous speed, } N_s = \frac{120 \times 50}{6} = 1000 \text{ rpm}$$

$$\text{Stalling speed} = 900 \text{ rpm}$$

$$\text{Slip at stalling torque, } s = \frac{1000 - 900}{1000} = 0.1$$

Slip at maximum torque; $S_{mT} = \frac{R_2}{X_2} = \frac{0.01}{X_2}$

\therefore $0.1 = \frac{0.01}{X_2}$
 $X_2 = 0.1 \Omega$

To obtain maximum torque at starting,

Let rotor resistance = R_2'

At starting, slip, $s = 1$

$$S_{mT} = \frac{R'_2}{X_2}$$

$$\Rightarrow 1 = \frac{R'_2}{0.1}$$

$$\Rightarrow R'_2 = 0.1 \text{ } \Omega/\text{phase}$$

The external resistance to be added,

$$\begin{aligned} R_{\text{ext}} &= 0.1 - 0.01 \\ &= 0.09 \text{ } \Omega/\text{phase} \end{aligned}$$

30. (b)

Given,

$$\eta = 0.9$$

Let,

$$P = \text{Stator copper loss}$$

$$= \text{Rotor copper loss} = \text{Iron loss}$$

$$\text{No load losses} = P_{NL}$$

$$\text{Mechanical loss} = P_{mL}$$

$$\text{No load losses} = \text{Iron loss} + \text{Mechanical losses}$$

$$P_{NL} = P + P_{mL}$$

$$3 P_{mL} = P + P_{mL}$$

$$P_{mL} = \frac{P}{2}$$

$$\text{Efficiency, } \eta = \frac{\text{Output Power}}{\text{Output power} + \text{losses}} = \frac{37}{37 + P + P + P + \frac{P}{2}}$$

$$0.90 = \frac{37}{37 + 3.5P}$$

$$P = 1.1746 \approx 1.175 \text{ kW}$$

$$\text{Airgap power} = P_{\text{output}} + \text{Mechanical losses} + \text{Rotor copper losses}$$

$$\text{Now slip, } s = \frac{\text{Rotor copper losses}}{\text{Air gap power}}$$

$$= \frac{1.175}{37 + \frac{1.175}{2} + 1.175} = 0.03$$

